



A Massive MIMO Sampling Detection Strategy Based on Denoising Diffusion Model

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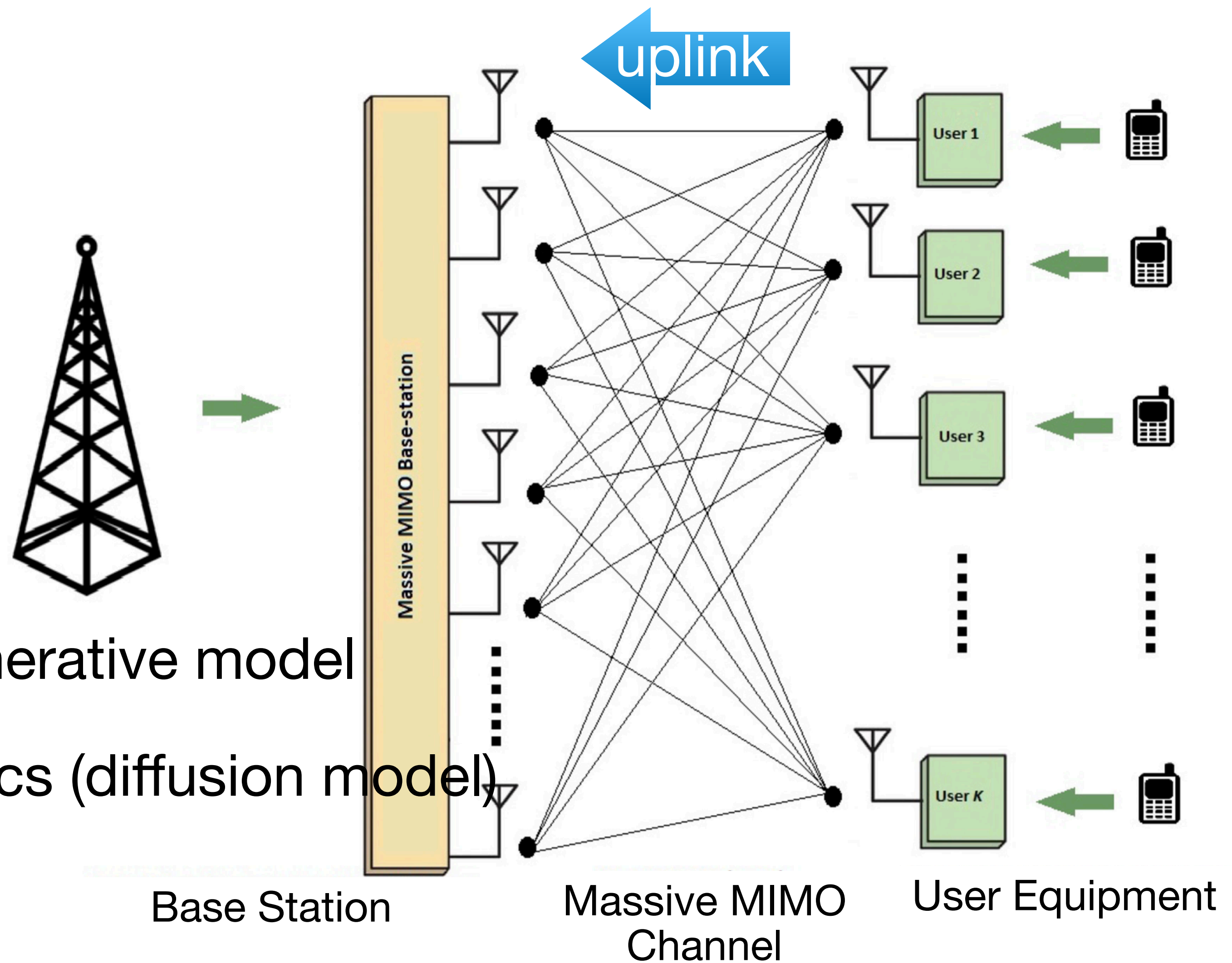


Outlines

- **Introduction**
- **Score-based Massive MIMO Detection**
- **Approximate Diffusion Detection Strategy**
- **Simulation results**
- **Conclusion**

Introduction

- Massive MIMO Detection
- On the uplink side



- ***Diffusion model***/score-based generative model
- non-equilibrium statistical physics (diffusion model)
- Denoising score matching
- Denoising diffusion probabilistic model (DDPM)
- Stochastic differential equation (SDE) for unification

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Score-based Massive MIMO Detection

- System Model $\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{n}$

$\mathbf{H} \in \mathbb{R}^{N \times K}$ perfectly-known flat Rayleigh fading channel matrix

$\mathbf{n} \in \mathbb{R}^N$ zero-mean additive white Gaussian noise with variance σ_0^2

$\mathcal{Q} = \{\pm 1, \pm 3, \dots, \pm\sqrt{M} - 1\}$ constellation set for M-ary QAM

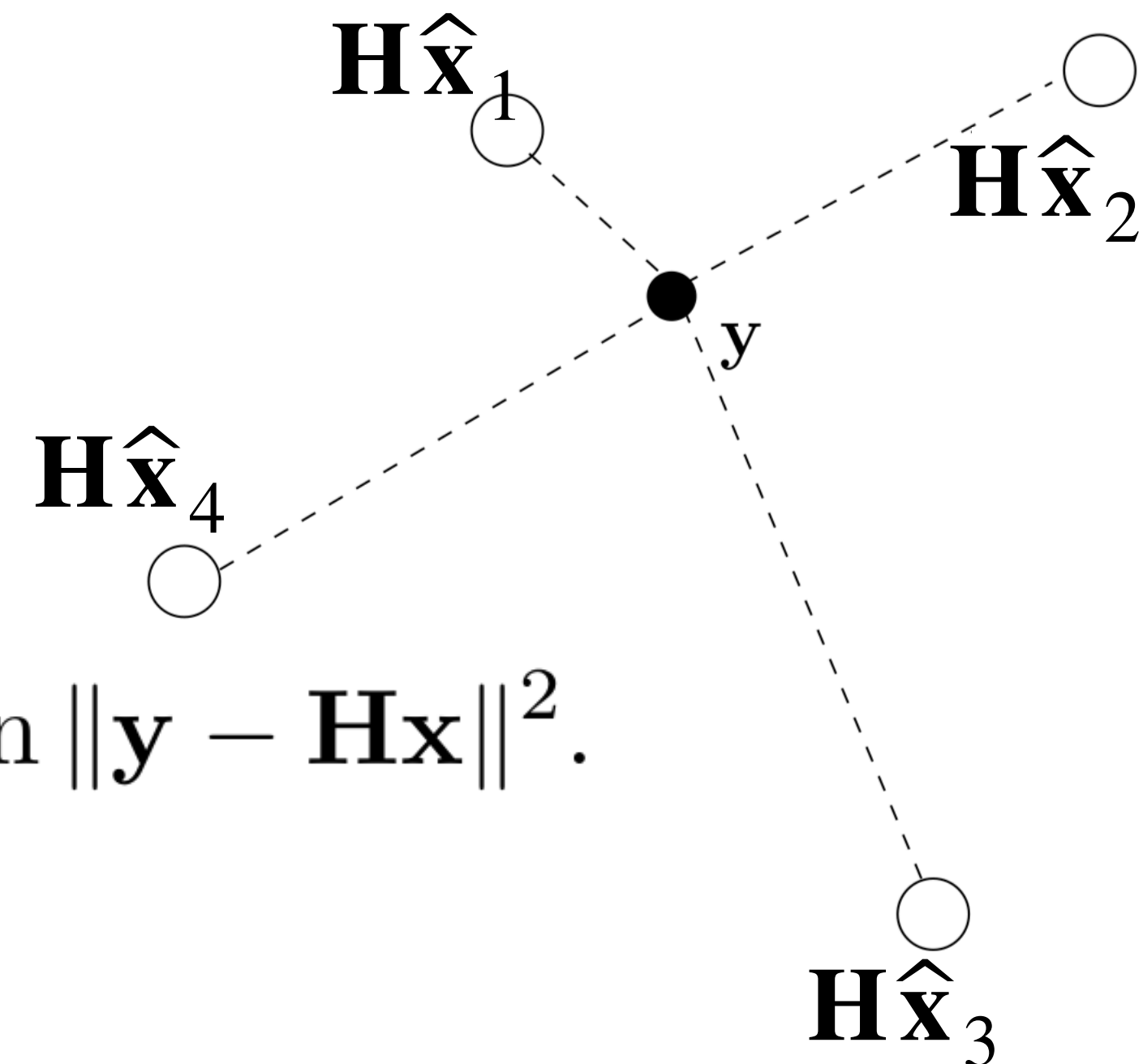
- MAP to ML detection

$$\hat{\mathbf{x}}_{\text{MAP}} = \arg \max_{\mathbf{x} \in \mathcal{Q}^K} p(\mathbf{x} | \mathbf{y}, \mathbf{H})$$

$$= \arg \max_{\mathbf{x} \in \mathcal{Q}^K} p(\mathbf{y} - \mathbf{H}\mathbf{x}) p(\mathbf{x}).$$

uniform
assumption
on prior

$$\hat{\mathbf{x}}_{\text{ML}} = \arg \min_{\mathbf{x} \in \mathcal{Q}^K} \|\mathbf{y} - \mathbf{H}\mathbf{x}\|^2.$$



Score-based Massive MIMO Detection

- Denoising Score-Matching

- Definition of *score*: $\mathbf{s}(\mathbf{x}) \triangleq \nabla_{\mathbf{x}} \log p(\mathbf{x})$

- score matching $\mathbf{s}_{\theta}(\mathbf{x})$ Approximate $\mathbf{s}(\mathbf{x})$

- Denoising score matching to perturb: $q_{\sigma}(\tilde{\mathbf{x}}) = \int p(\mathbf{x}) q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x}) d\mathbf{x}$

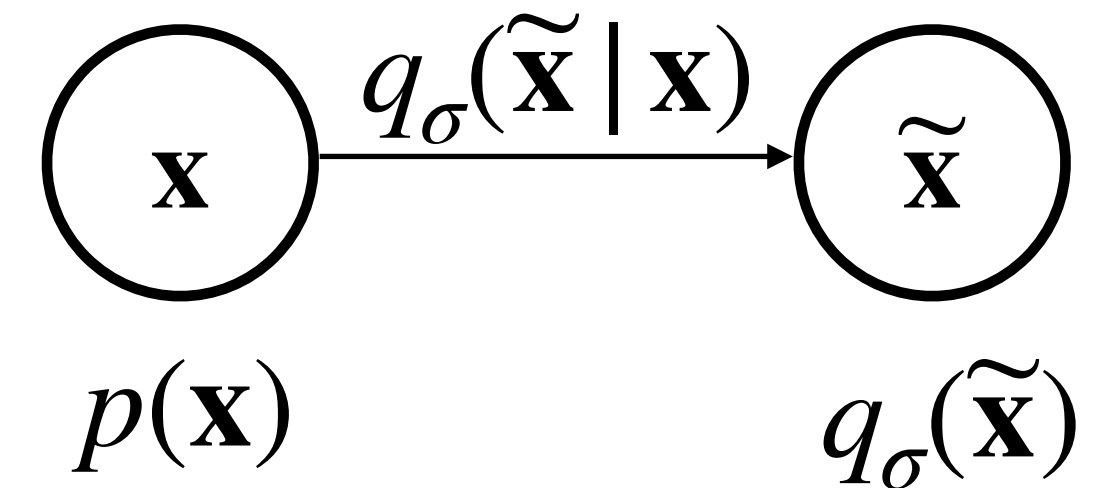
With Gaussian kernel (perturbation) $q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x}) = \mathcal{N}(\tilde{\mathbf{x}}; \mathbf{x}, \sigma^2 \mathbf{I})$

- Optimization criterion

$$\theta = \arg \min_{\theta} \mathbb{E}_{q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x})p(\mathbf{x})} [\|\mathbf{s}_{\theta}(\tilde{\mathbf{x}}) - \nabla_{\tilde{\mathbf{x}}} \log q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x})\|^2]$$

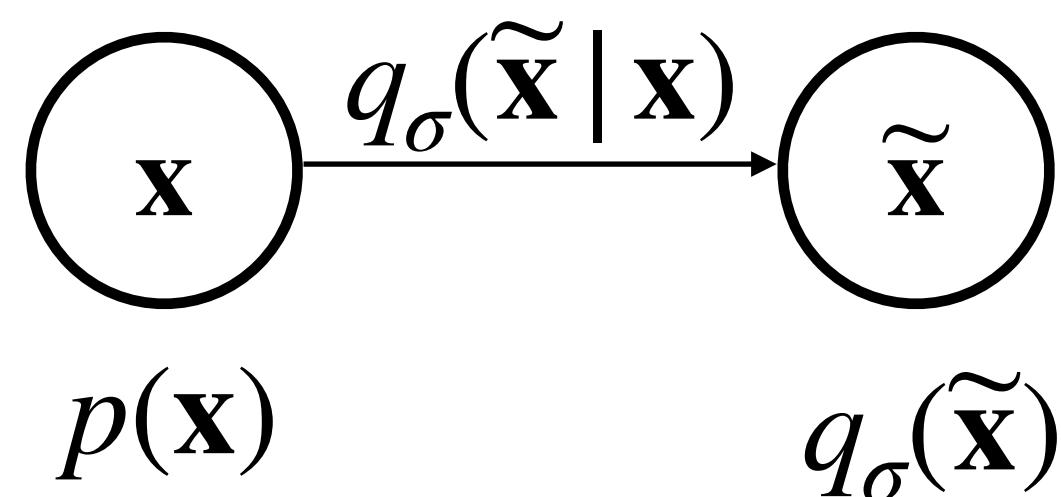
- As long as the perturbation is small enough:

$$\mathbf{s}_{\theta}^*(\mathbf{x}) = \nabla_{\mathbf{x}} \log q_{\sigma}(\mathbf{x}) \approx \nabla_{\mathbf{x}} \log p(\mathbf{x})$$

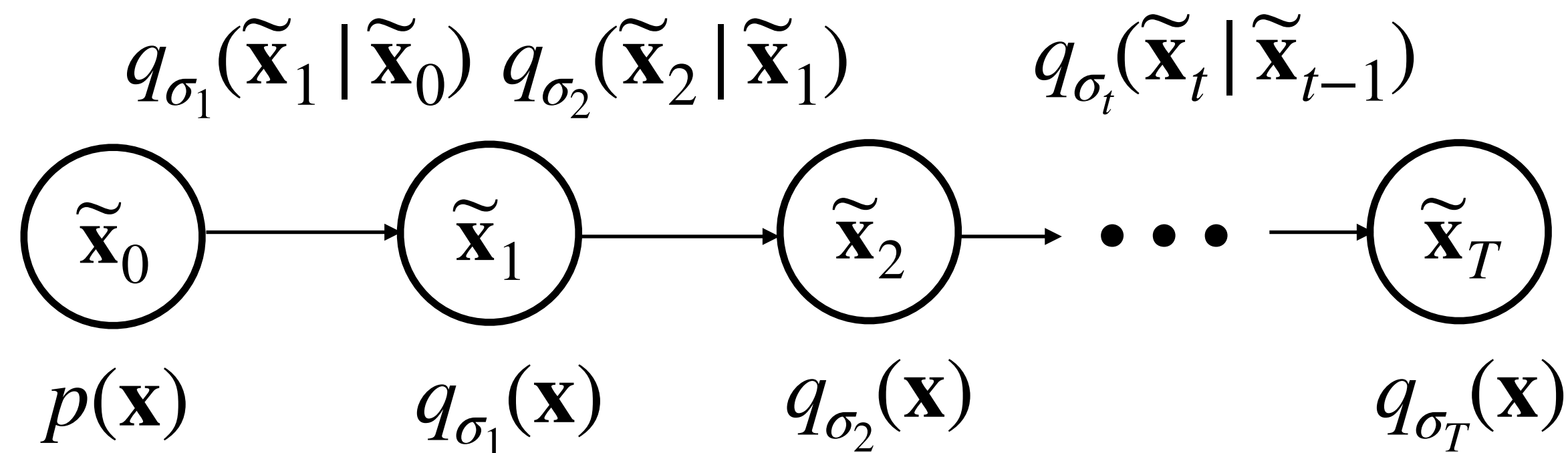
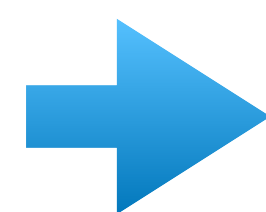


Score-based Massive MIMO Detection

- Annealed Langevin Strategy



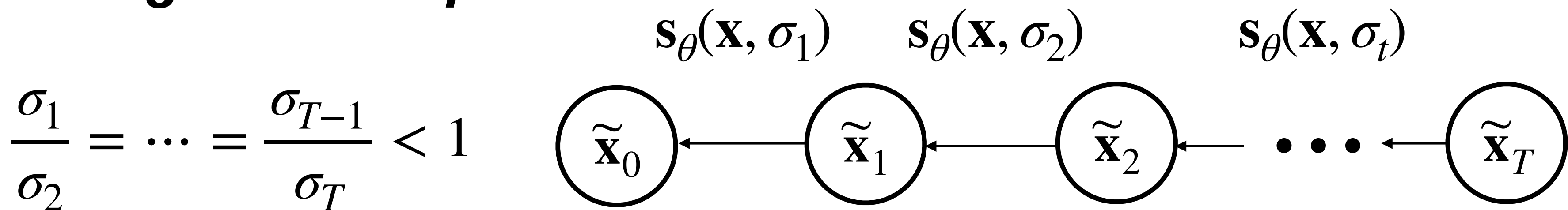
irregular fluctuation
estimation inaccuracy
slow mixing problem



forward diffusion processes

For the Gaussian kernel: $q_{\sigma_t}(\tilde{\mathbf{x}}_t | \mathbf{x}) \sim \mathcal{N}(\tilde{\mathbf{x}}_t; \mathbf{x}, \sigma_t^2 \mathbf{I})$

Reverse generative process



$$\frac{\sigma_1}{\sigma_2} = \dots = \frac{\sigma_{T-1}}{\sigma_T} < 1$$

$$\hat{\mathbf{x}}_i = \hat{\mathbf{x}}_{i-1} + \frac{\delta_t}{2} \mathbf{s}_\theta(\hat{\mathbf{x}}_{i-1}, \sigma_t) + \sqrt{\delta_t} \mathbf{w}_i, i = 1, 2, \dots, L_A$$

$$\begin{aligned} \hat{\mathbf{x}}_0 &= \tilde{\mathbf{x}}_t \\ \tilde{\mathbf{x}}_{t-1} &= \hat{\mathbf{x}}_{L_A} \end{aligned}$$

Score-based Massive MIMO Detection

- Annealed Langevin sampling detection (ALS) [1]

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{n}$$

- *Posterior score* matters
- Applying the Bayes' rule

$$\nabla_{\hat{\mathbf{x}}_t} \log p(\hat{\mathbf{x}}_t | \mathbf{y}) = \nabla_{\hat{\mathbf{x}}_t} \log p(\hat{\mathbf{x}}_t) + \nabla_{\hat{\mathbf{x}}_t} \log p(\mathbf{y} | \hat{\mathbf{x}}_t)$$

- SNIPS Method: evaluate the score explicitly
 - Involving an SVD decomposition of the channel matrix \mathbf{H}
- list detection $\mathcal{L} = \{\hat{\mathbf{x}}^{(1)}, \hat{\mathbf{x}}^{(2)}, \dots, \hat{\mathbf{x}}^{(S)} | \hat{\mathbf{x}} \sim p(\mathbf{x} | \mathbf{y})\}$

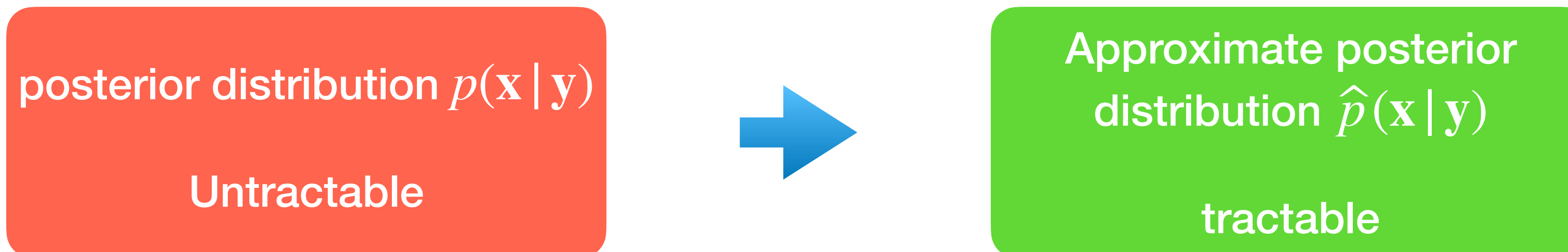
$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x} \in \mathcal{L}} \|\mathbf{y} - \mathbf{H}\mathbf{x}\|^2$$

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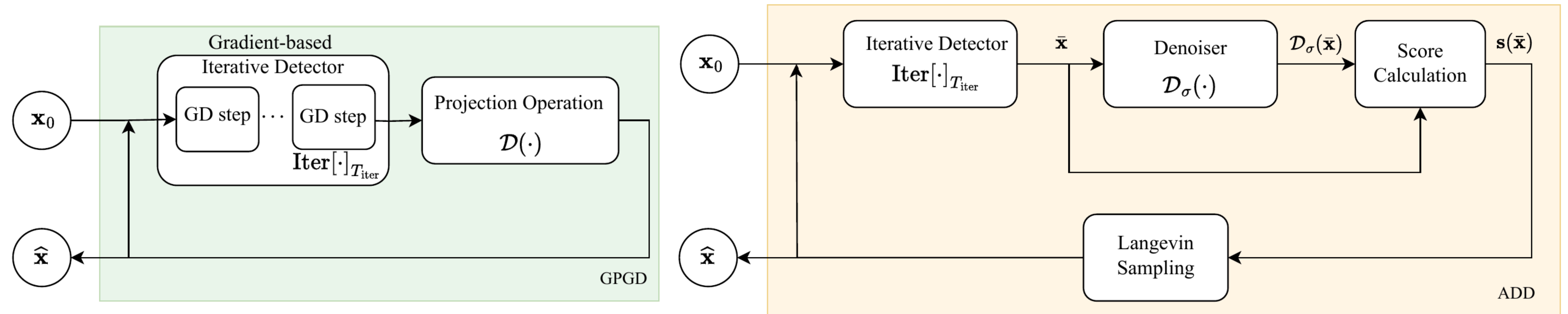
Approximate Diffusion Detection Strategy

- **objective**
 - to circumvent the SVD decomposition
 - To find a flexible sampling structure that can be extended to ***deep generative detection network***
- **Main idea**
 - Incorporate with an iterative detection method to sample from an *approximate posterior distribution*



Approximate Diffusion Detection Strategy

- Inspiration to propose Approximate Diffusion Detection (ADD) Strategy



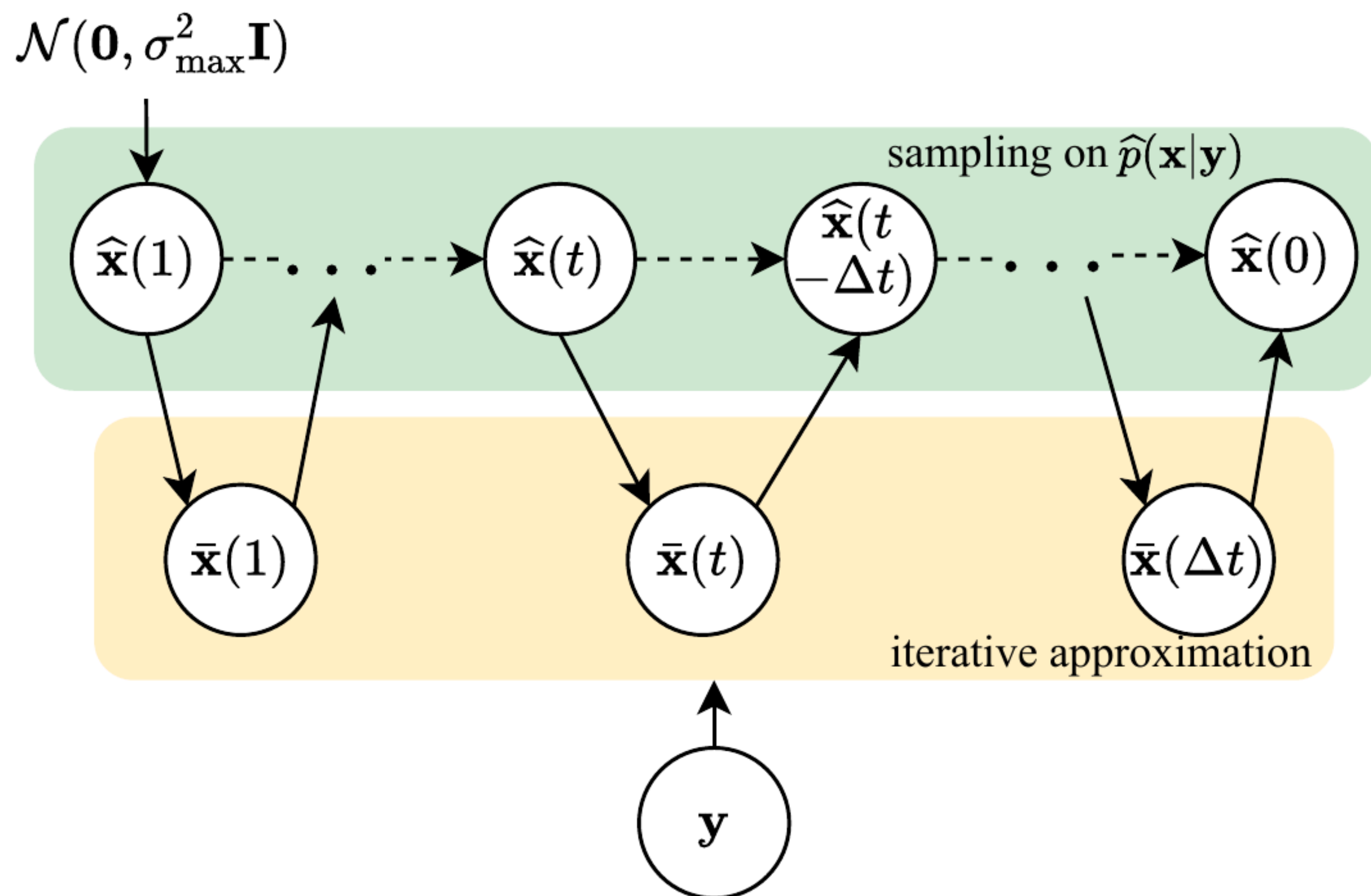
- Give a direction in the sampling space

$$\hat{\mathbf{x}}_i = \hat{\mathbf{x}}_{i-1} + \frac{\delta_t}{2} \mathbf{s}_\theta(\hat{\mathbf{x}}_{i-1}, \sigma_t) + \sqrt{\delta_t} \mathbf{w}_i, i = 1, 2, \dots, L_A \quad \text{Random walk}$$

- Apply a deterministic method stochastically

Approximate Diffusion Detection Strategy

- Structure



- Details on the score calculation

- The denoiser

- 1-D Lattice Gaussian Distribution (LGD)

$$p_{\mathcal{Q}}(x_k = \hat{x}_k; \bar{x}_k, \sigma) \triangleq \frac{1}{Z_{\mathcal{Q}}} \exp\left(\frac{-\|\hat{x}_k - \bar{x}_k\|^2}{2\sigma^2}\right), \hat{x}_k \in \mathcal{Q},$$

$$Z_{\mathcal{Q}} = \sum_{\hat{x}_k \in \mathcal{Q}} \exp\left(\frac{-\|\hat{x}_k - \bar{x}_k\|^2}{2\sigma^2}\right)$$

- Tweedie's identity

$$\mathbf{s}(\bar{\mathbf{x}}) = \frac{\mathcal{D}(\bar{\mathbf{x}}) - \bar{\mathbf{x}}}{\sigma^2}$$

Score-based Massive MIMO Detection

- Complexity
- Take conjugated gradient descent (CGD) as an instance

ADD	ALS
$O(NK^2 + T(NK + T_{\text{iter}}K^2 + MK))$	$O(NK^2 + L_A T(K^2 + MK))$
calculation of Hermitian matrix $\mathbf{H}^T \mathbf{H}$	SVD computation

- **Extension to deep generative detection network**

For the Gaussian kernel: $\nabla_{\tilde{\mathbf{x}}} \log q_{\sigma}(\tilde{\mathbf{x}} | \mathbf{x}) = -(\tilde{\mathbf{x}} - \mathbf{x})/\sigma^2$

Training of a denoising score network $\ell(\theta; \sigma) = \mathbb{E}_{p(\mathbf{x})} \mathbb{E}_{\tilde{\mathbf{x}} \sim q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x})} \left[\left\| \mathbf{s}_{\theta}(\tilde{\mathbf{x}}, \sigma) + \frac{\tilde{\mathbf{x}} - \mathbf{x}}{\sigma^2} \right\|^2 \right]$

Consider the reparameterization $\tilde{\mathbf{x}} = \mathbf{x} + \sigma \mathbf{z}$

$$\ell(\theta; \sigma) = \mathbb{E}_{p(\mathbf{x})} \mathbb{E}_{\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \left[\left\| \mathbf{s}_{\theta}(\tilde{\mathbf{x}}, \sigma) + \frac{\mathbf{z}}{\sigma} \right\|^2 \right]$$

unsupervised training

Minimum MSE denoiser $\mathbf{s}(\tilde{\mathbf{x}}, \sigma) = \frac{\mathcal{D}_{\sigma}(\tilde{\mathbf{x}}) - \tilde{\mathbf{x}}}{\sigma^2}$

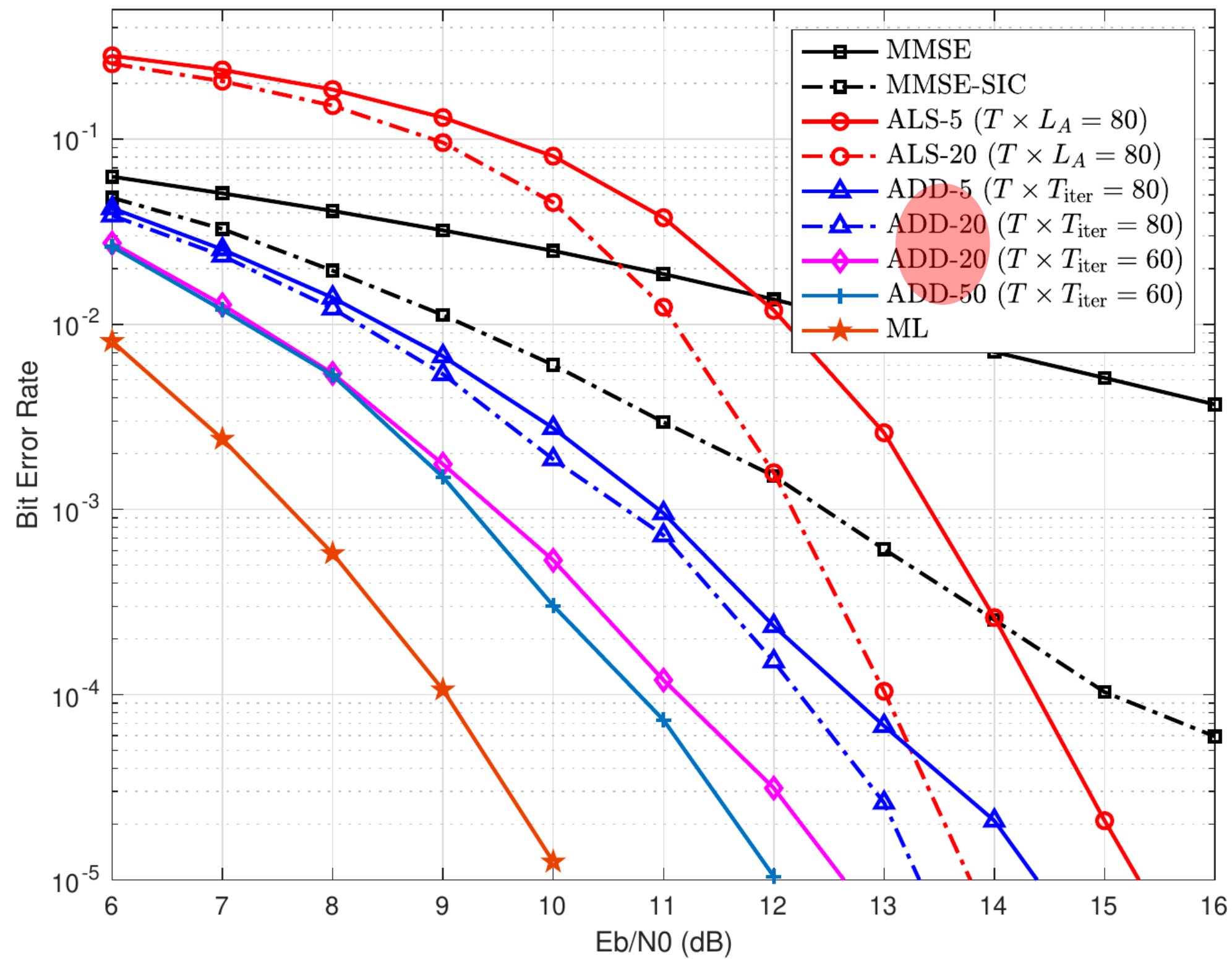
$$\ell(\theta; \sigma) = \mathbb{E}_{p(\mathbf{x})} \mathbb{E}_{\tilde{\mathbf{x}} \sim q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x})} \left[\left\| \mathcal{D}_{\theta, \sigma}(\tilde{\mathbf{x}}) - \mathbf{x} \right\|^2 \right]$$

supervised training

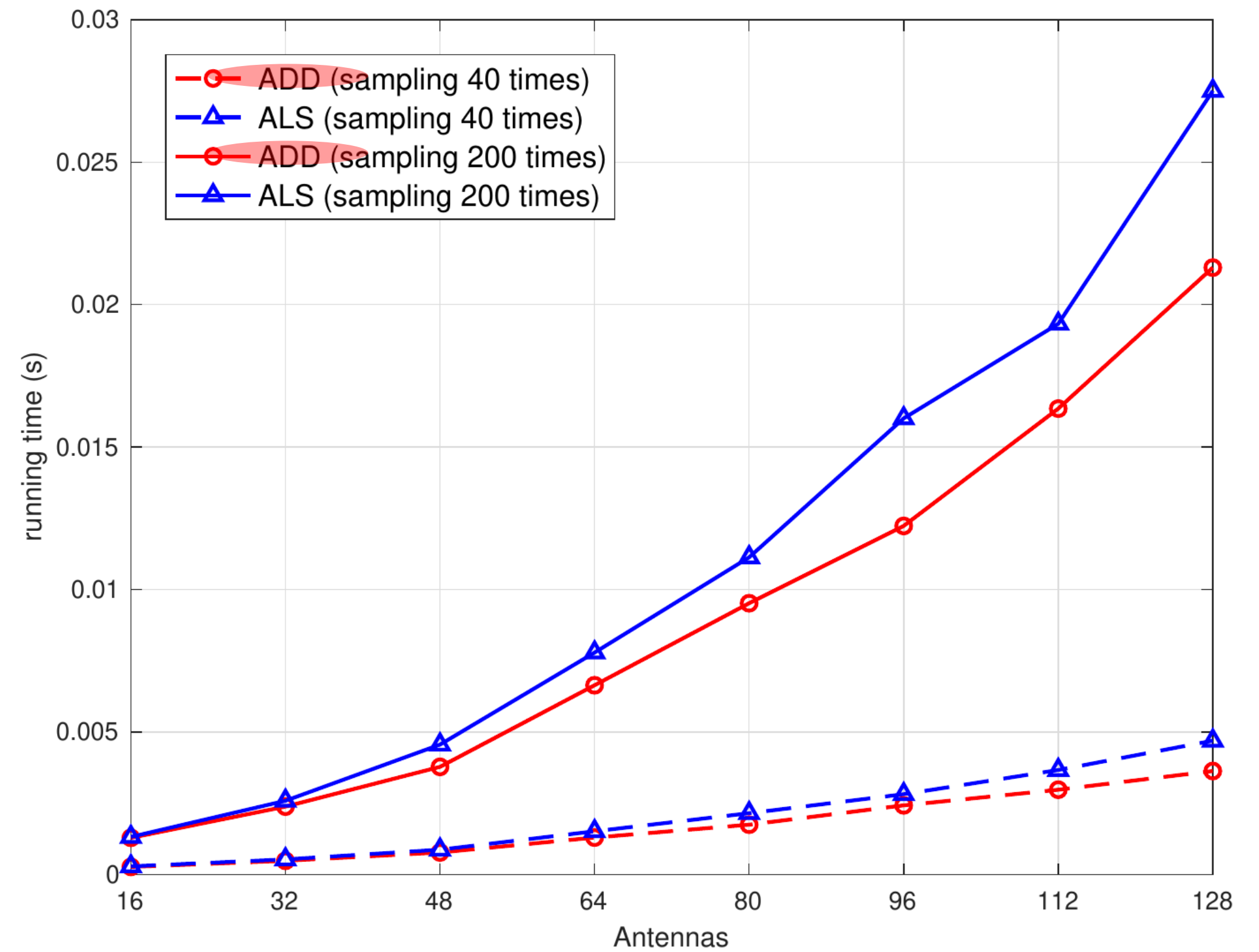
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Simulation results



32 × 32 QPSK
Performance



N = K
Running time

A better performance-complexity trade-off

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Conclusion

- Circumventing the SVD calculation of the existing score-based detection
- A strategy that can be applied to other gradient-based methods flexibly
- Applying a deterministic algorithm stochastically

- **Future work**
 - Network structure for the extended ***deep generative detection network***
 - Formulation of the proposal distribution



Thanks for listening, any questions?

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